

FIG. 2A

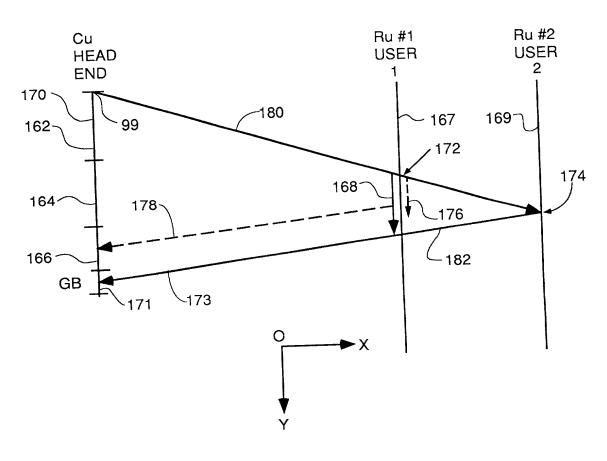
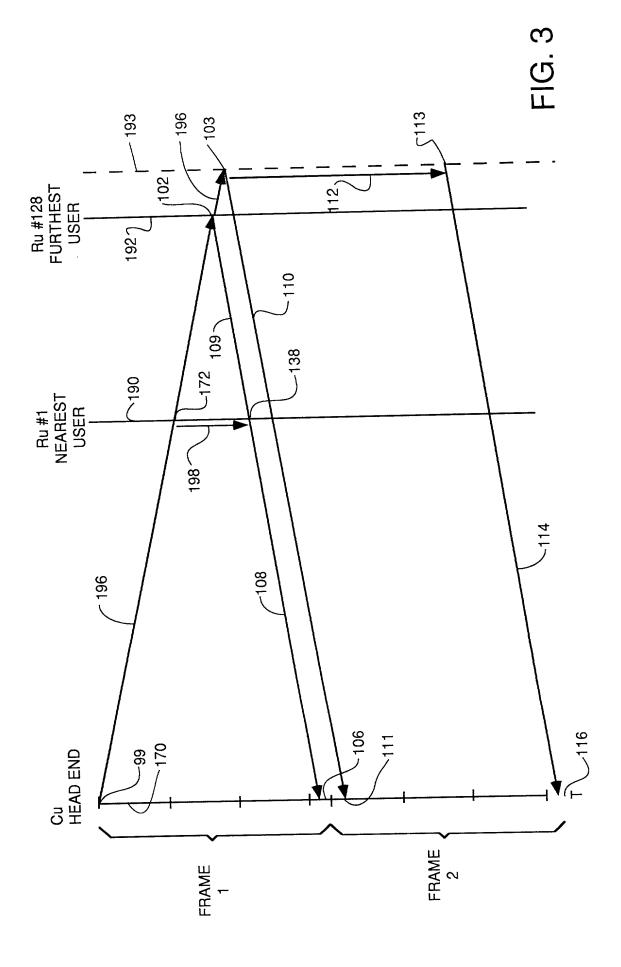
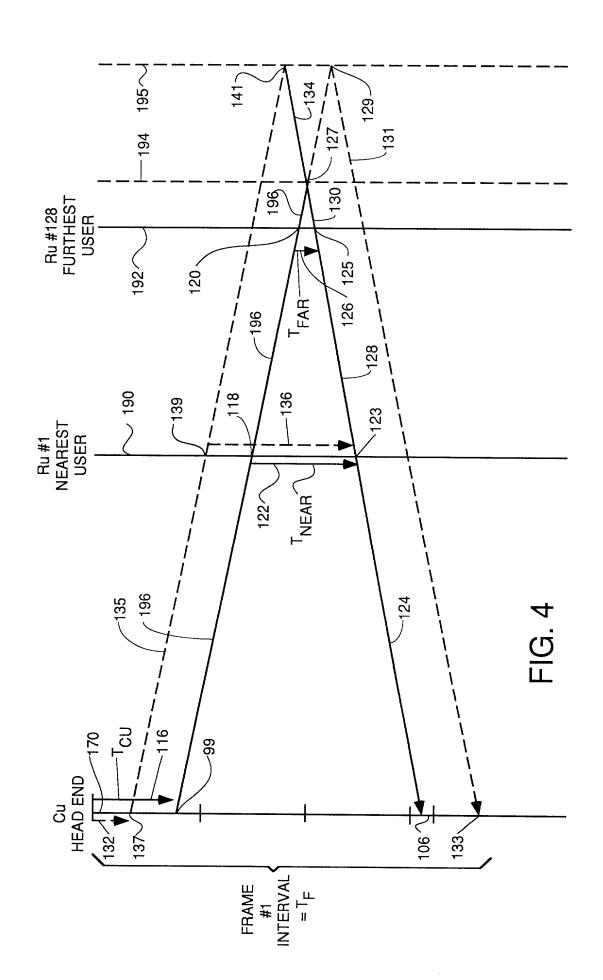
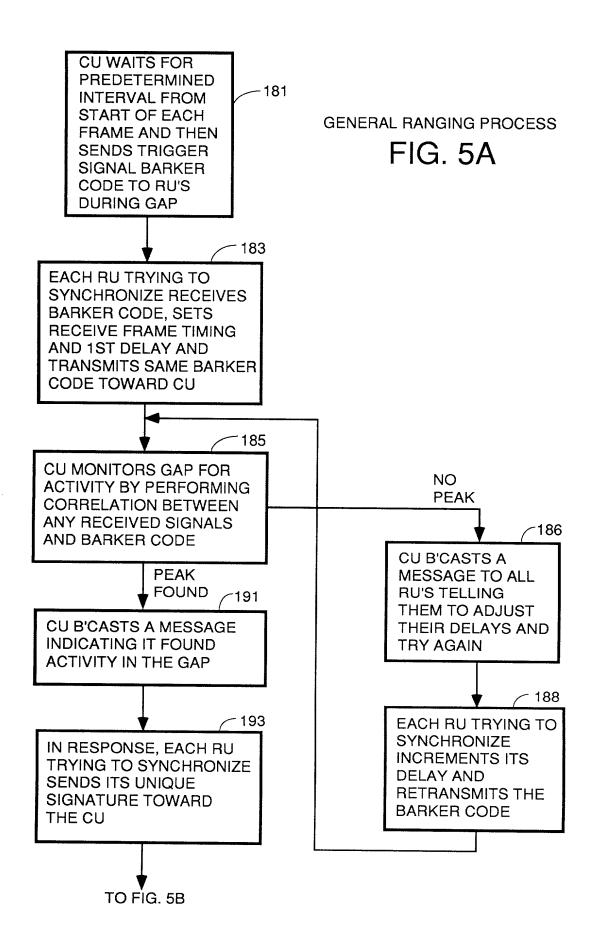
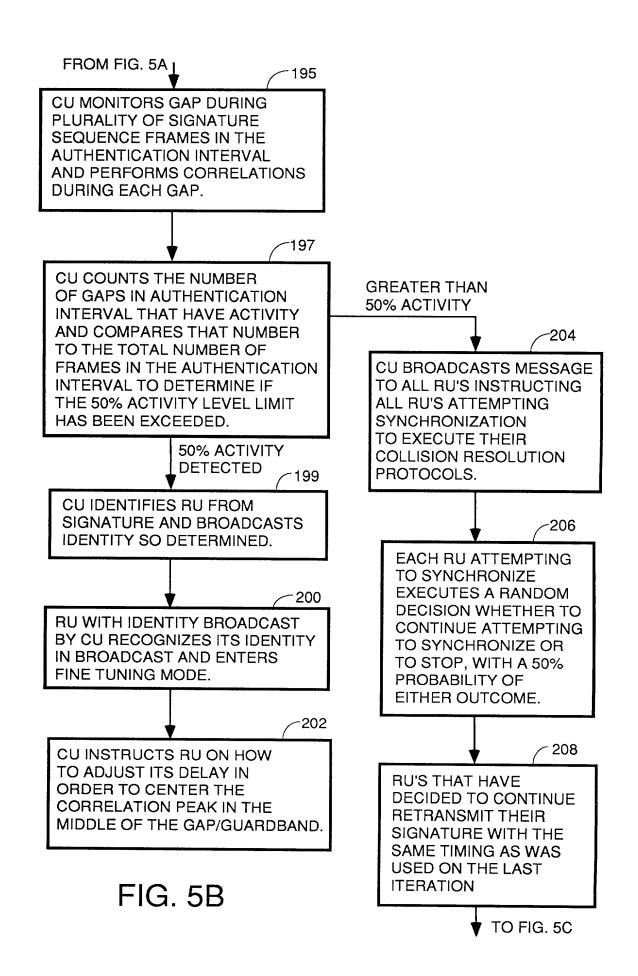


FIG. 2B









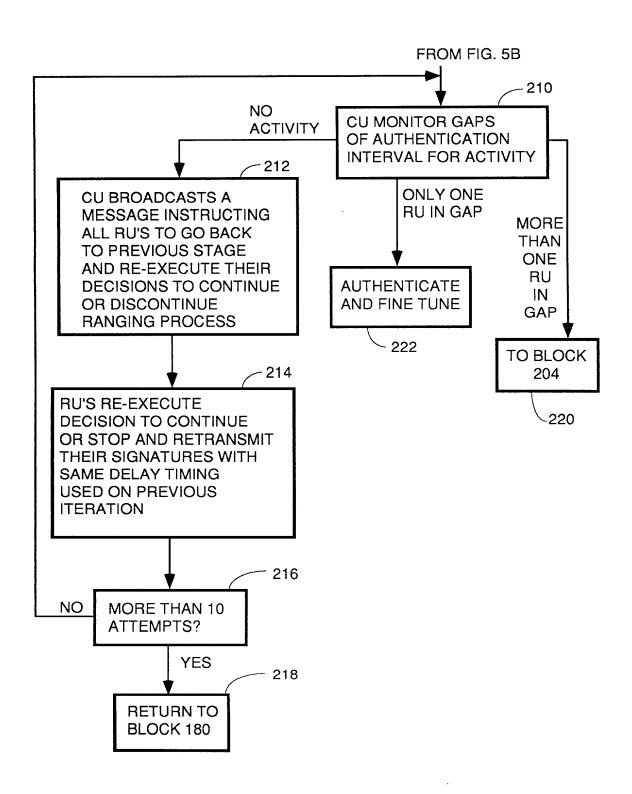


FIG. 5C

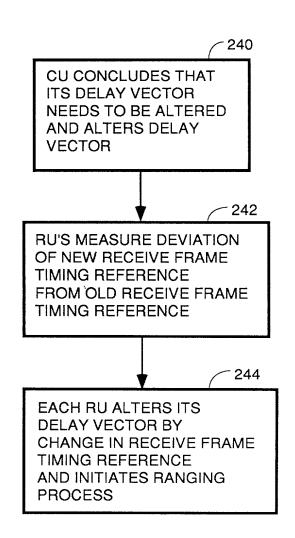


FIG. 6
DEAD RECKONING RE-SYNC

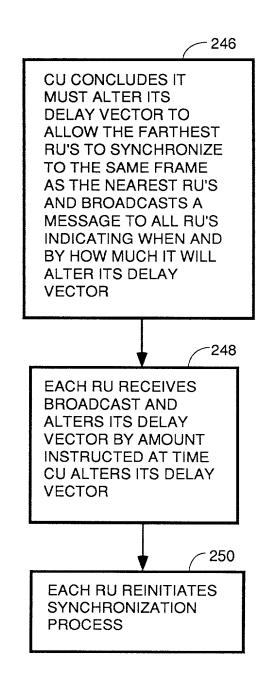
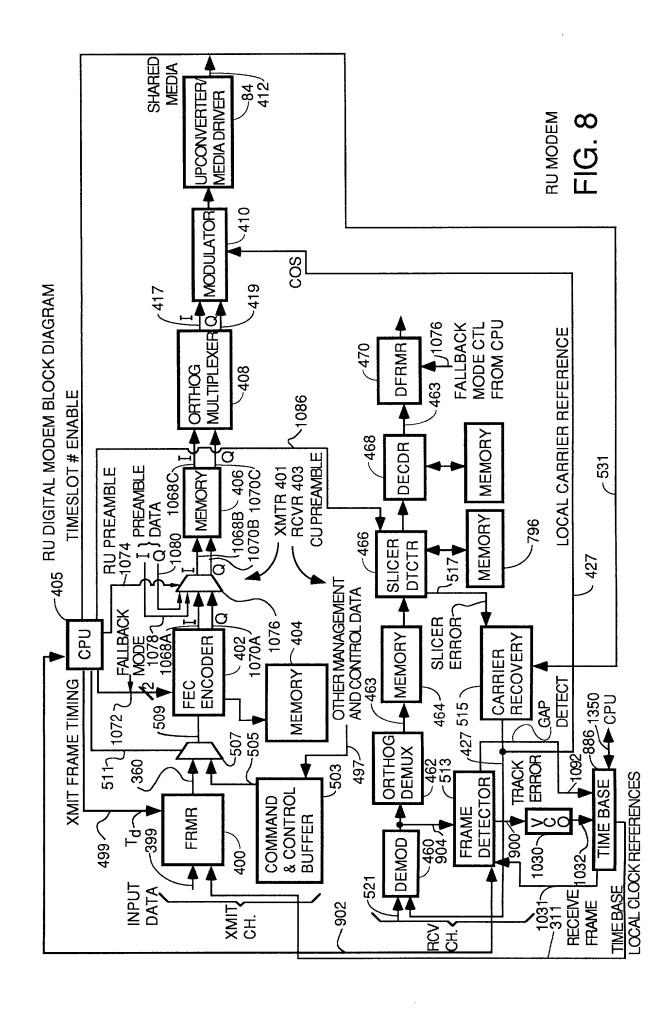


FIG. 7
PRECURSOR EMBODIMENT



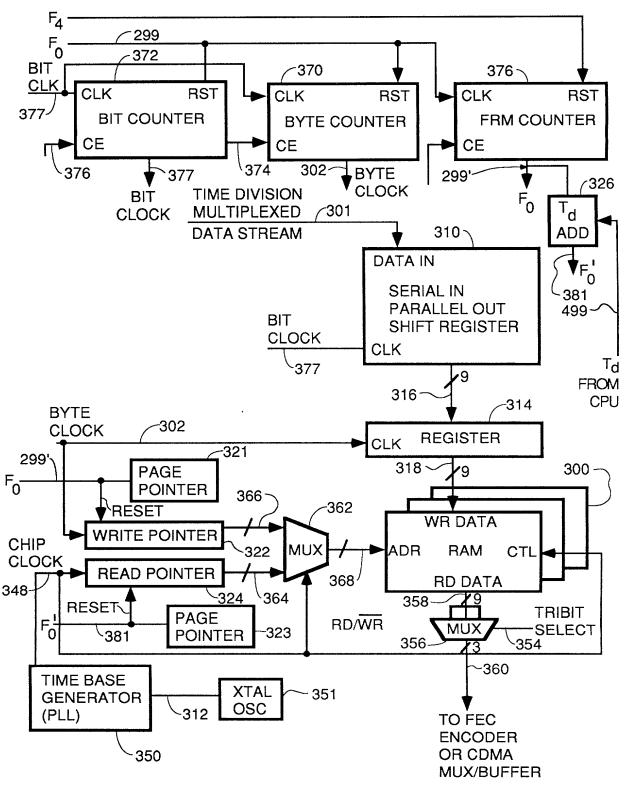


FIG. 9

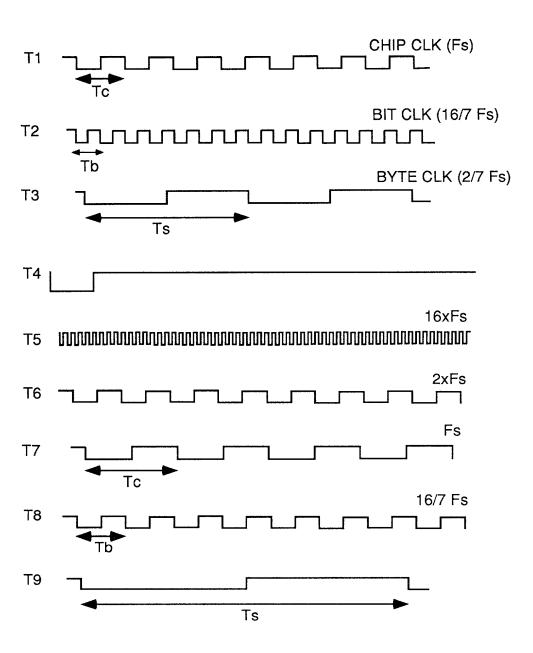


FIG. 10

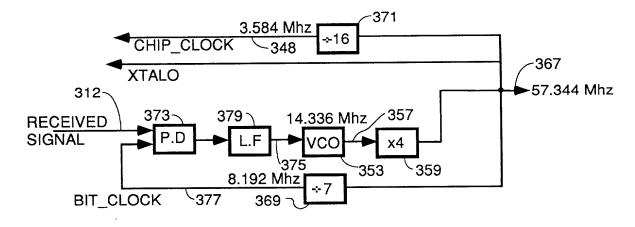
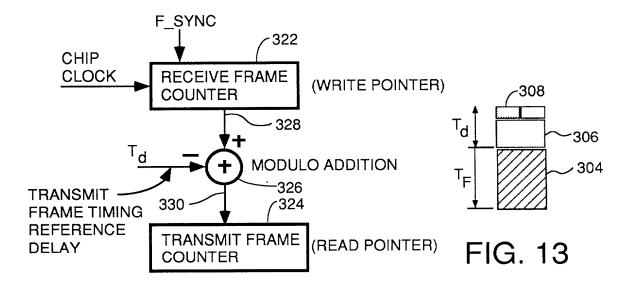
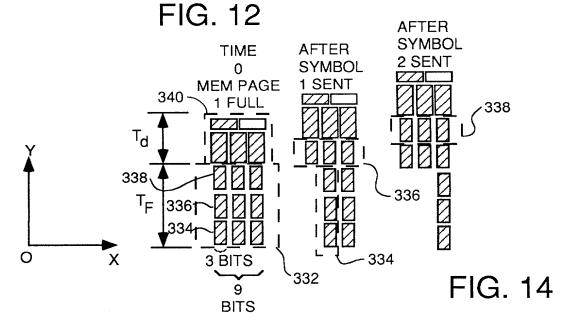


FIG. 11





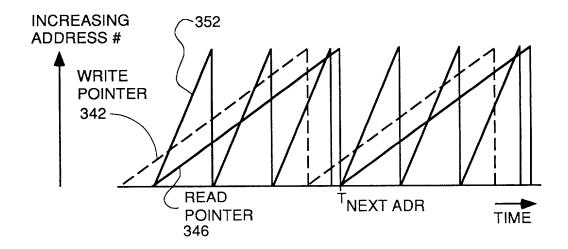


FIG. 15

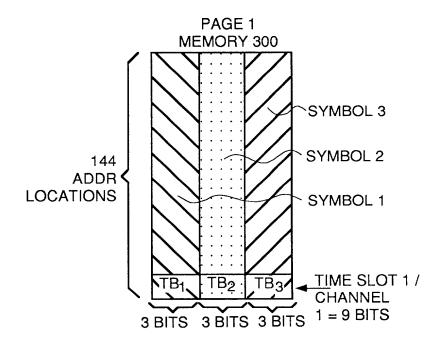


FIG. 16

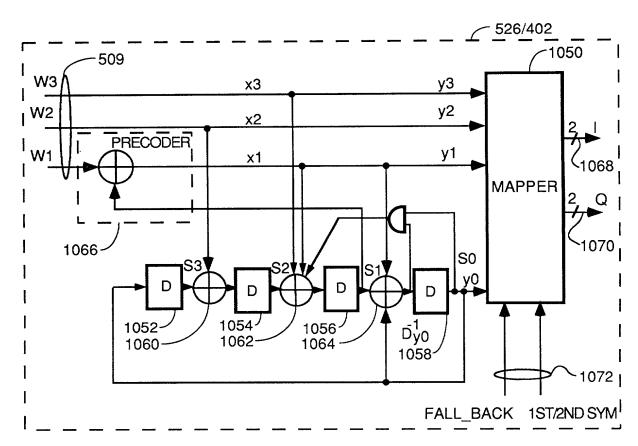


FIG. 17

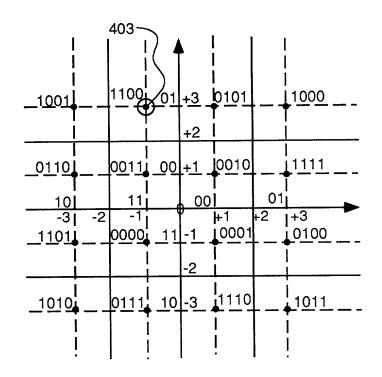


FIG. 18

	0000	111	111	
	0001	001	111	= 1 - j
	0010	001	001	= 1+j
	0011	111	001	= -1+ j
	0100	011	111	= 3 - j
	0101	001	011	= 1 + 3 * j
	0110	101	001	= -3 + j
	0111	111	101	= -1 - 3 <u>∗ j</u>
	1000	011	011	=+3 + 3 * j
	1001	101	011	= -3 + 3 * j
	1010	101	101	= -3 - 3 * j
403~	1011	011	101	= 3 - 3 * j
403	1100	111	011)	<u>= -1+3* j</u>
	1101	101	111	= -3 - j
	1110	001	101	= 1 - 3 * j
	1111	011	001	= 3 + j

FIG. 19

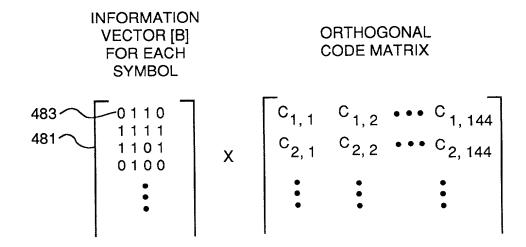


FIG. 20A

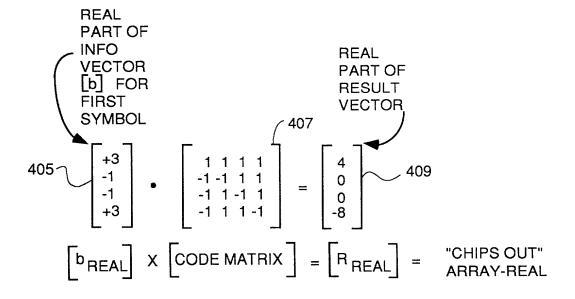
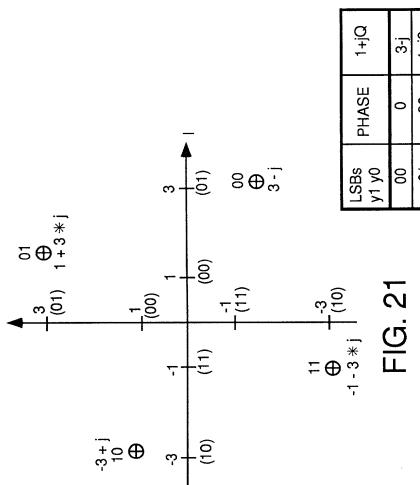


FIG. 20B

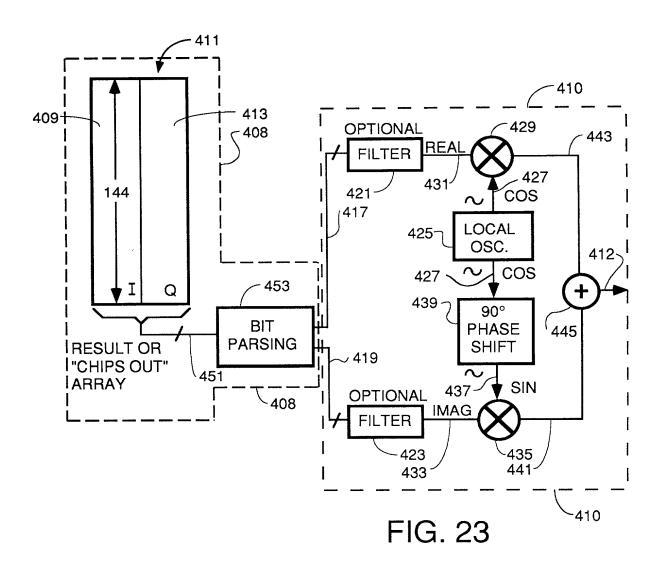
MAPPING FOR FALL-BACK MODE - LSB'S

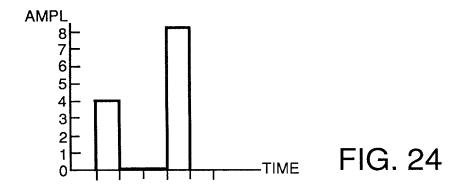


ă V V	y3 y2	8	01	10	11	
	1+jQ	3-j	1+j3	-3+j	-1-j3	
	PHASE	0	06	180	06-	
	LSBs y1 y0	00	01	10	11	

MSBs difference symbol) 1+jQ wHEN wHEN wHEN wHEN symbol) 1+jQ wHEN wHEN wHEN wHEN wHEN wHEN wHEN wHEN					
difference WHEN WHEN V (2nd-1st LSB=00 LSB=01 LSB=0	1+jQ WHEN LSB=11	-1-j3	3-j	1+j3	-3+j
difference WHEN (2nd-1st LSB=00 lsymbol) 3-j 90 1+j3 180 -3+j -90 -1-j3	1+jQ WHEN LSB=10	-3+j	-1-j3	3-j	1+j3
difference (2nd-1st symbol) 0 0 90 -90 -90	1+jQ WHEN LSB=01	1+j3	-3+j	-1-j3	3-j
	1+jQ WHEN LSB=00	3-j	1+j3	-3+j	-1-j3
MSBs y3 y2 00 01 10	PHASE difference (2nd-1st symbol)	0	06	180	-90
	MSBs y3 y2	00	10	10	11

LSB & MSB FALLBACK MODE MAPPINGS FIG. 22





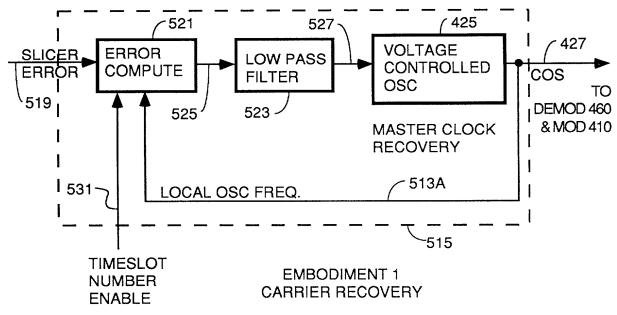
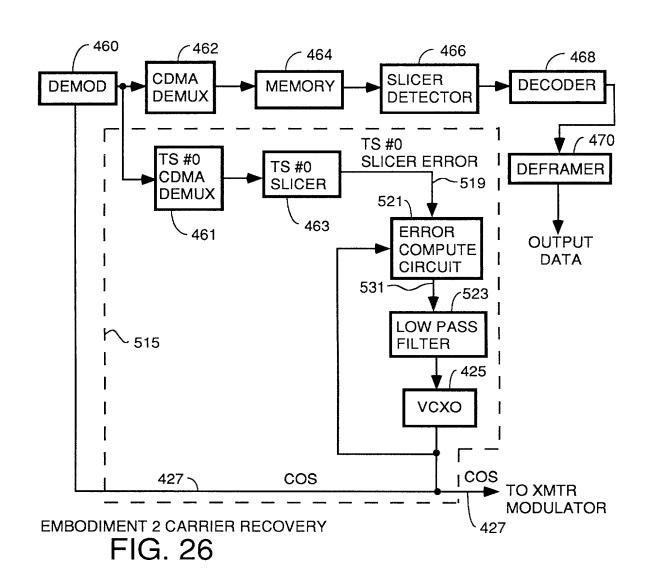


FIG. 25



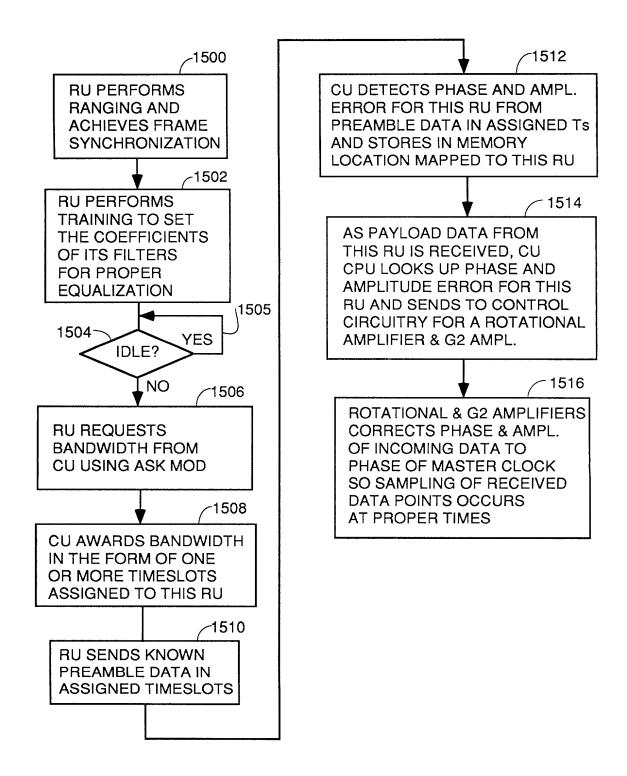
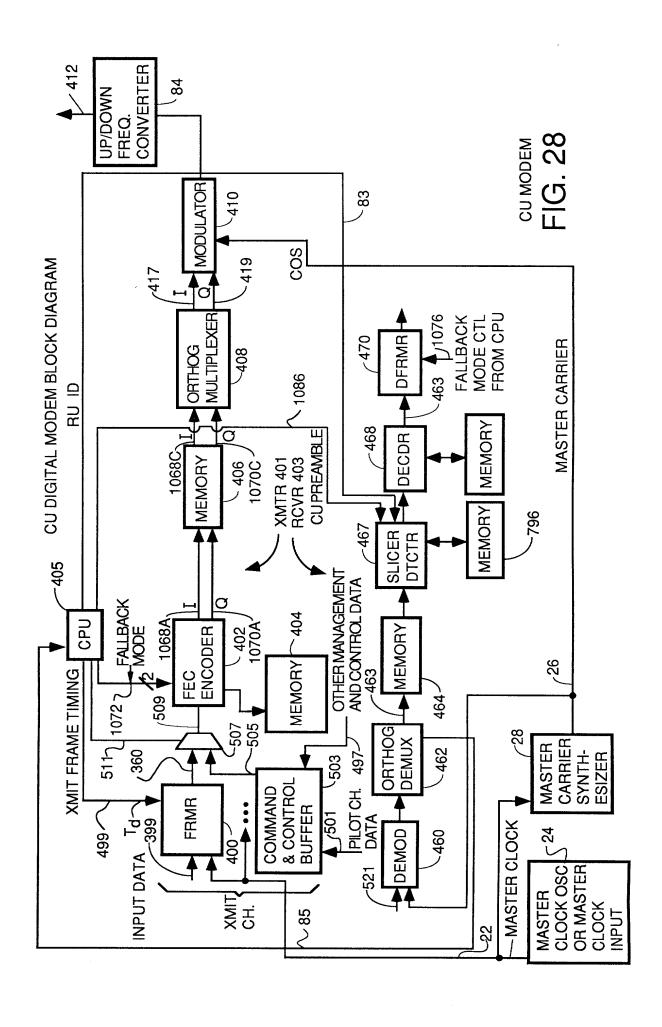


FIG. 27



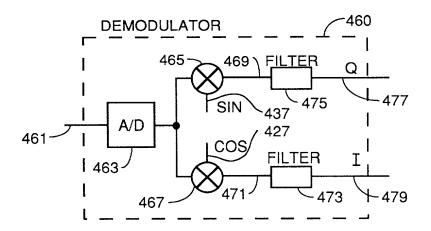
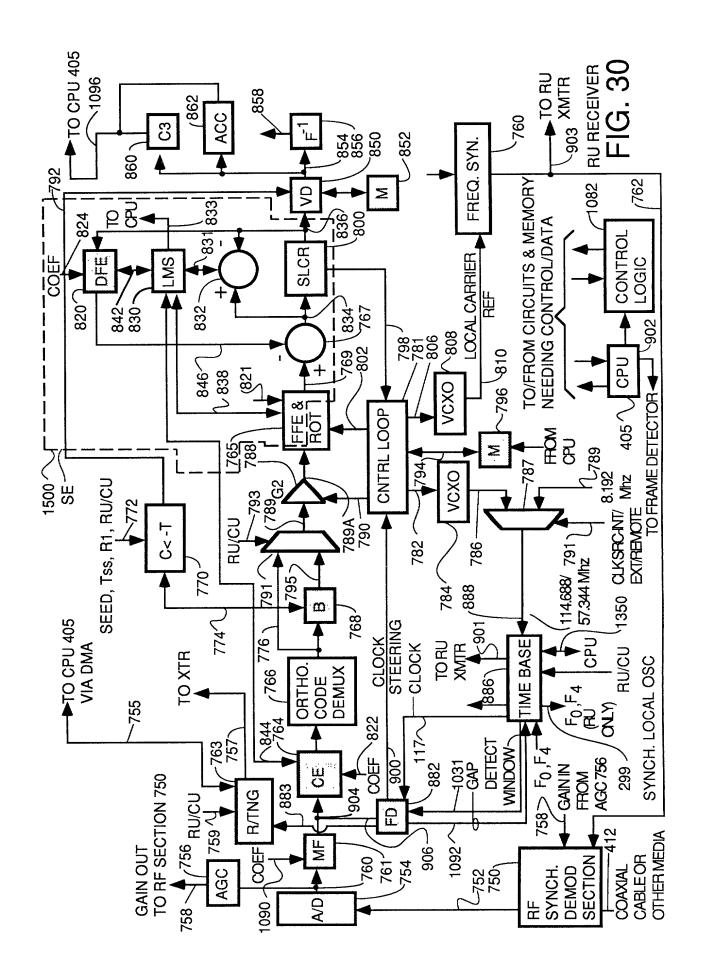
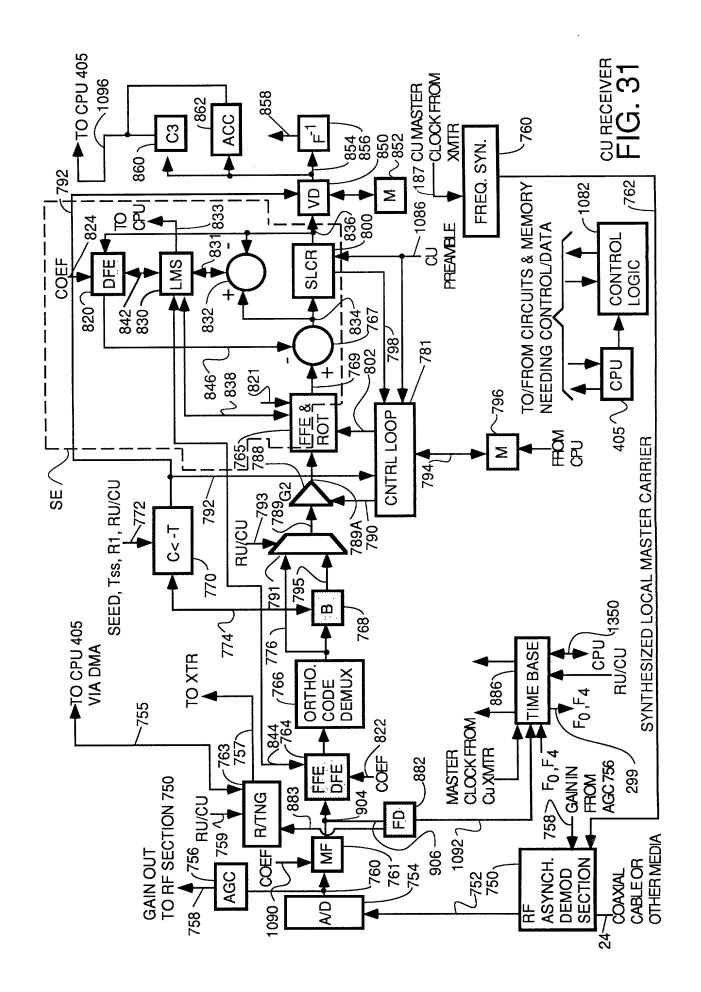
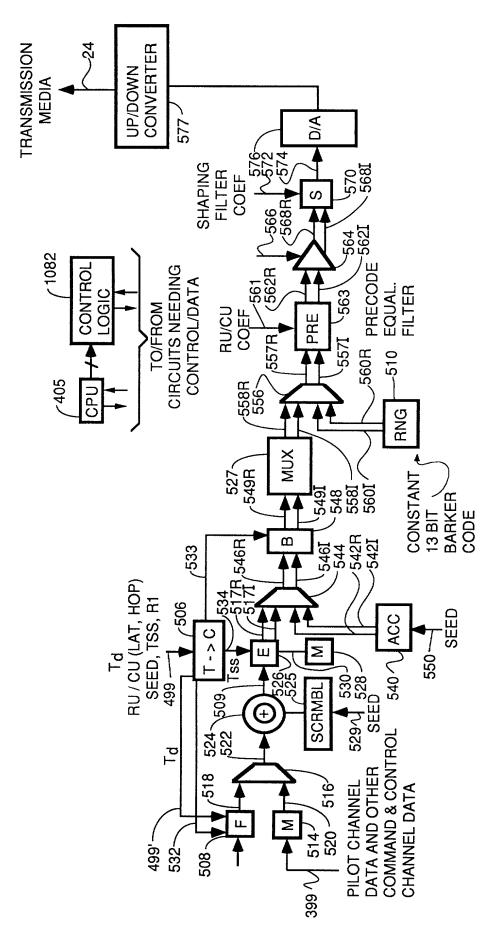


FIG. 29

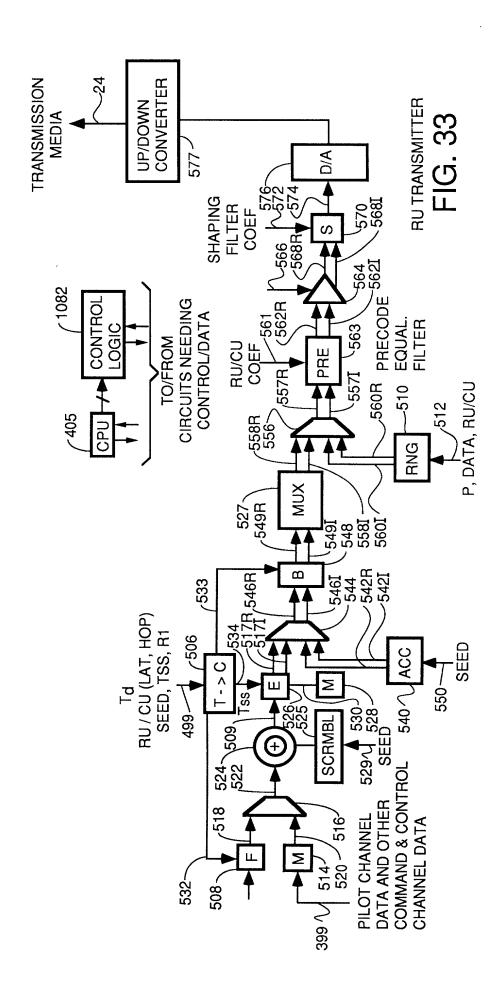


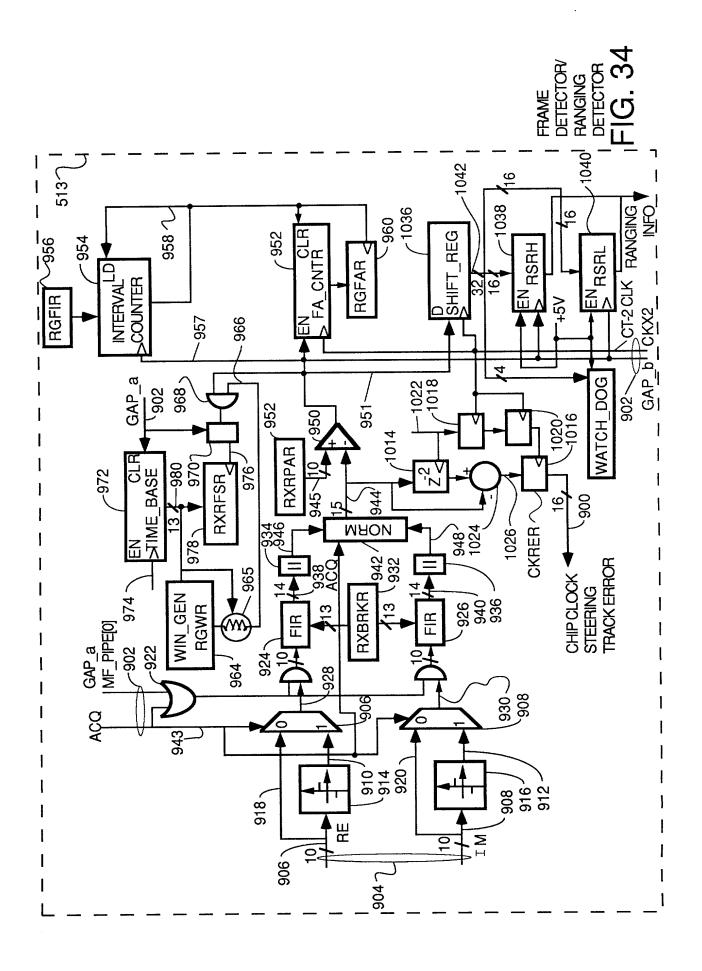


٠.,



CU TRANSMITTER FIG. 32





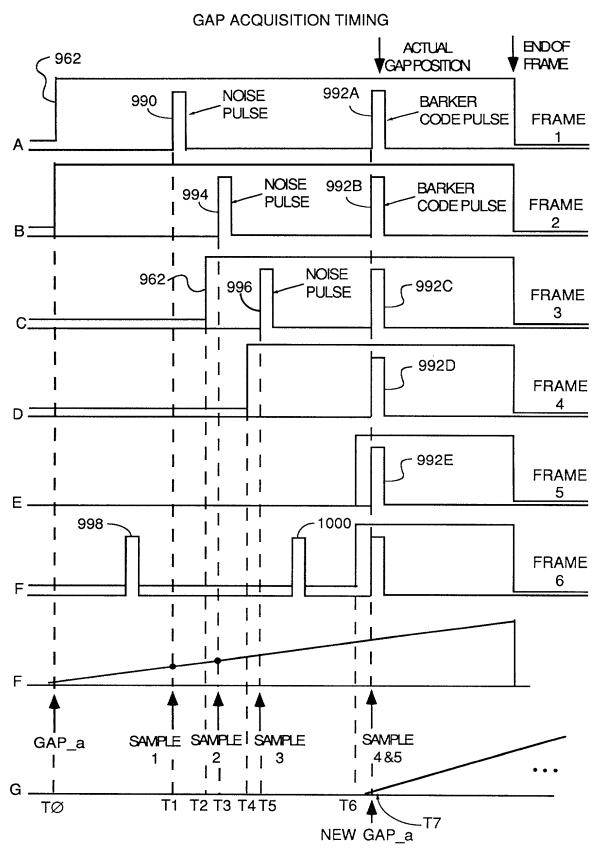


FIG. 35

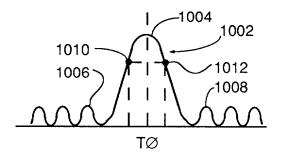


FIG. 36

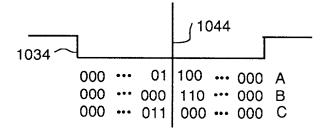
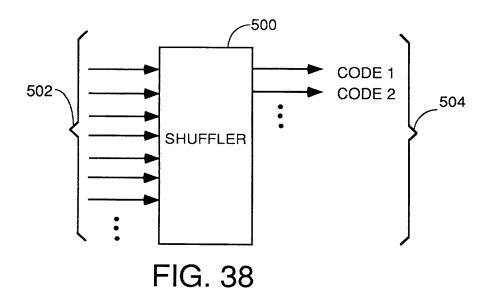
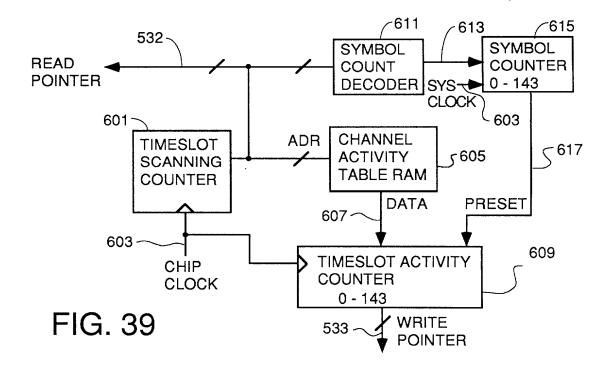
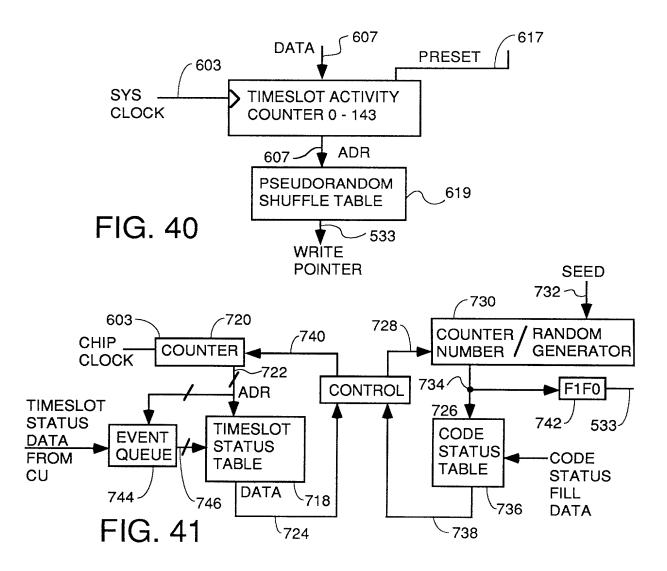
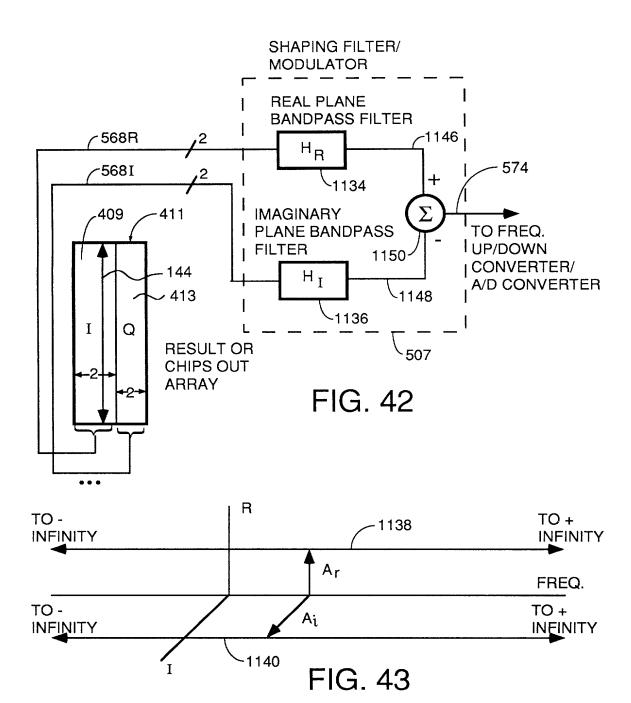


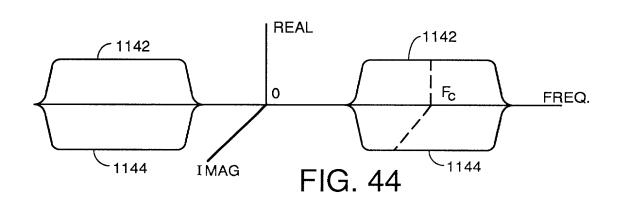
FIG. 37
FINE TUNING TO
CENTER BARKER CODE











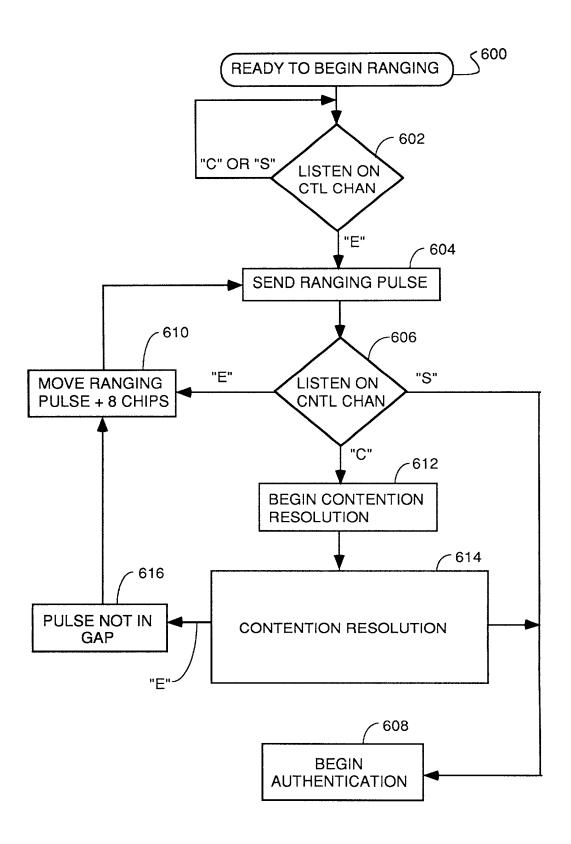
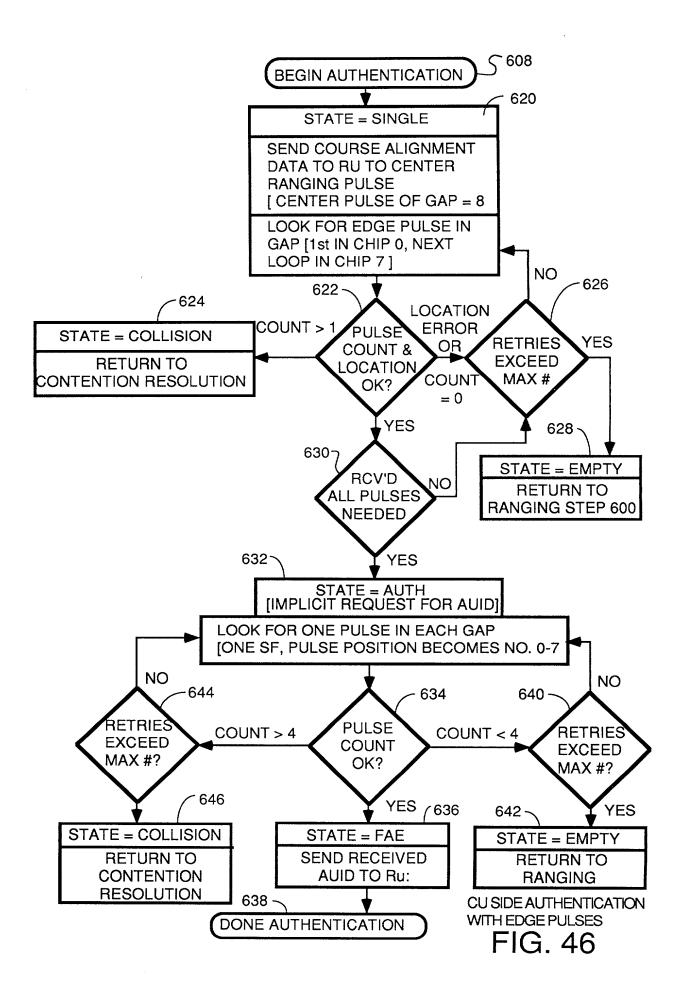
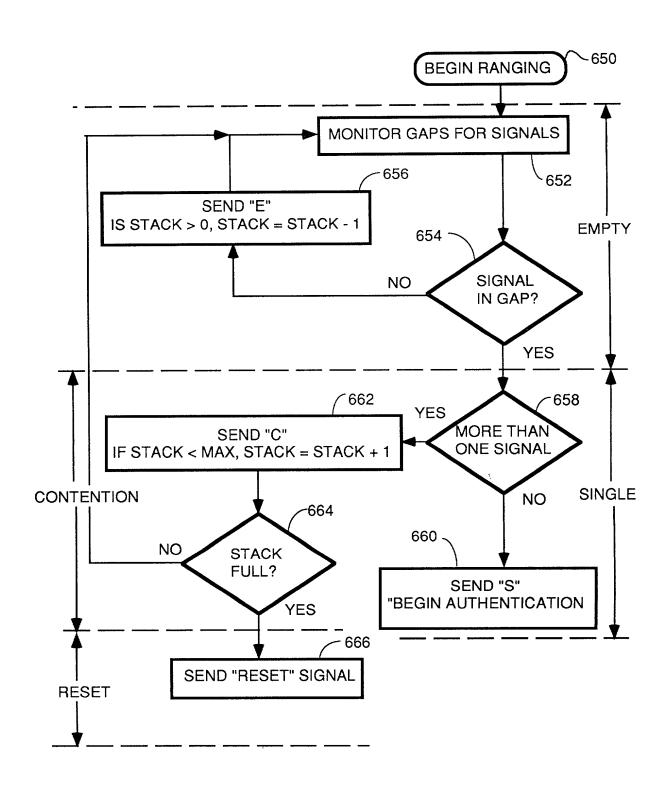
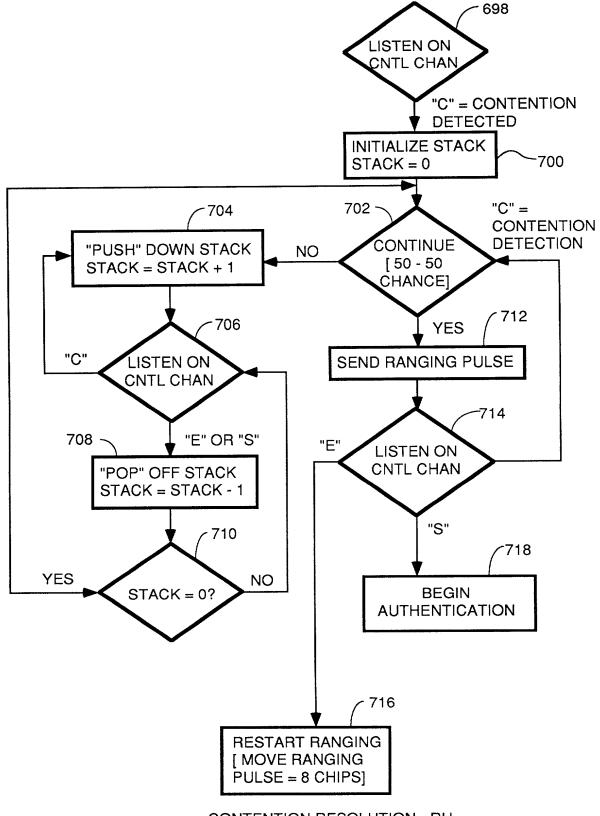


FIG. 45



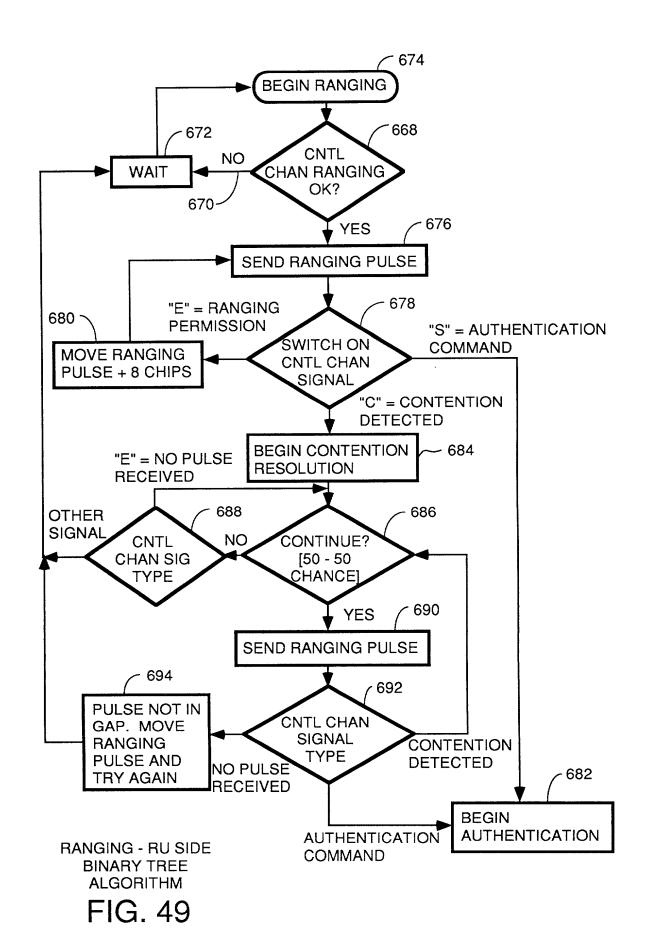


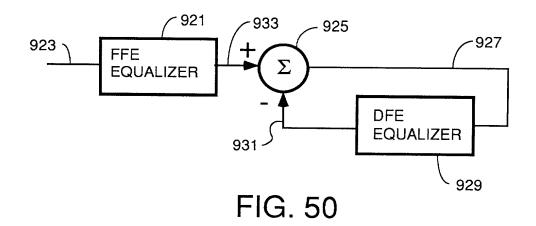
cu ranging and contention resolution FIG. 47

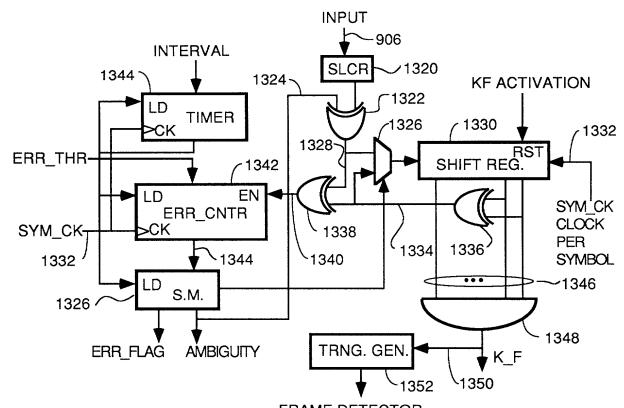


CONTENTION RESOLUTION - RUUSING BINARY STACK

FIG. 48

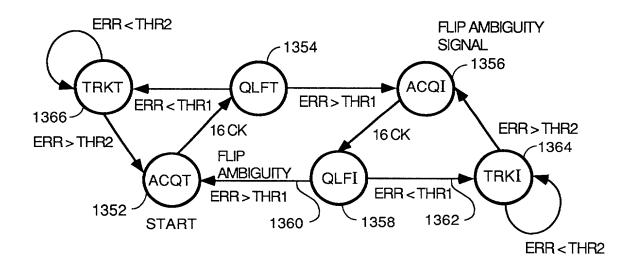






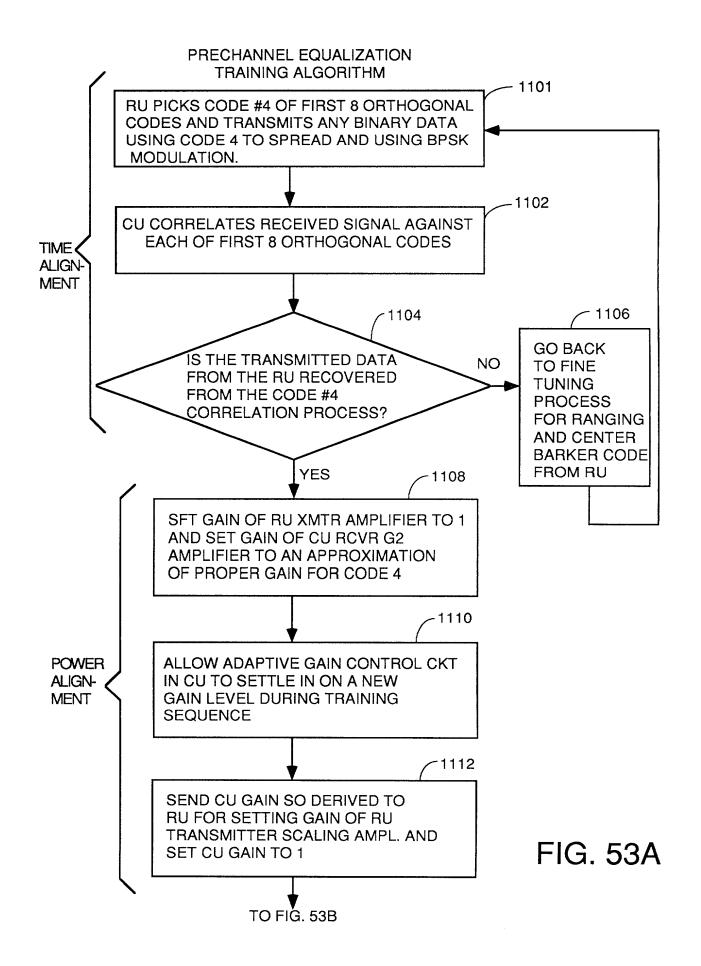
FRAME DETECTOR
FRAME SYNC/KILOFRAME DETECT

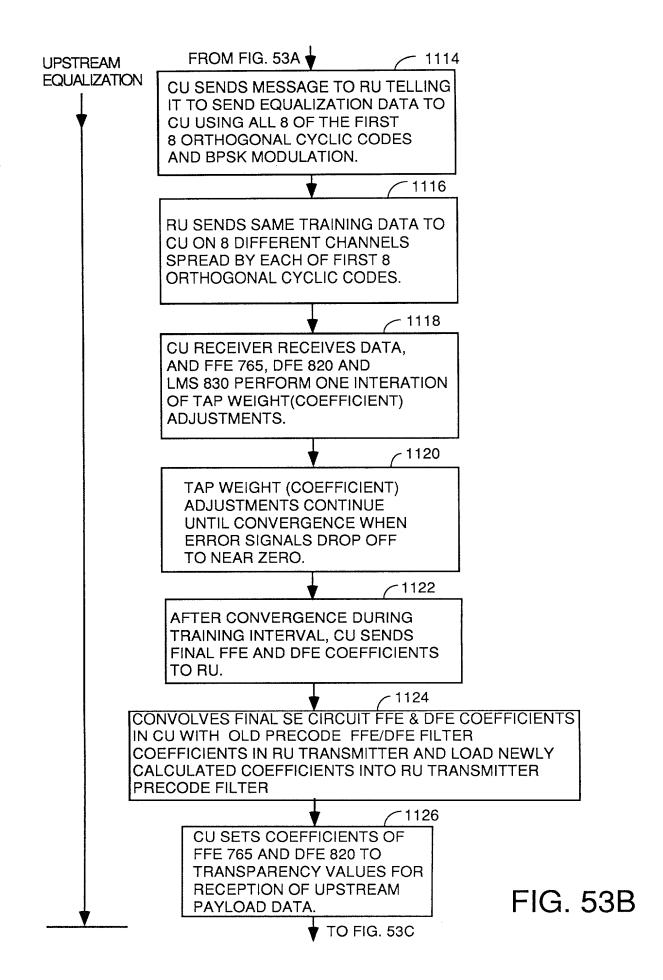
FIG. 51



STATE MACHINE

FIG. 52





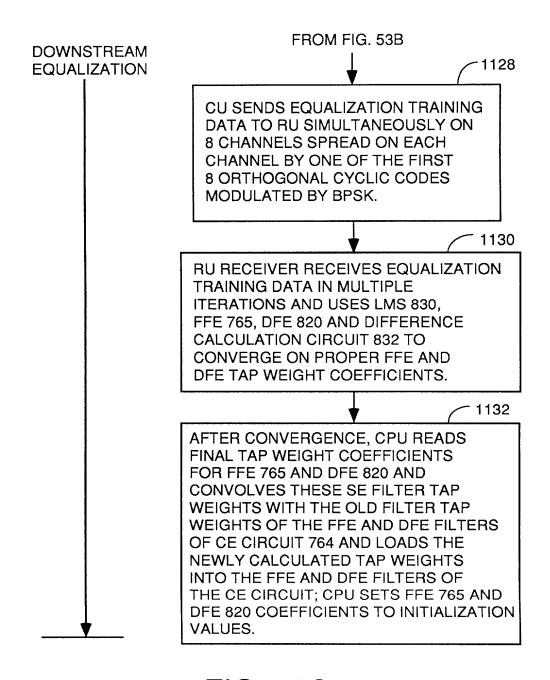


FIG. 53C

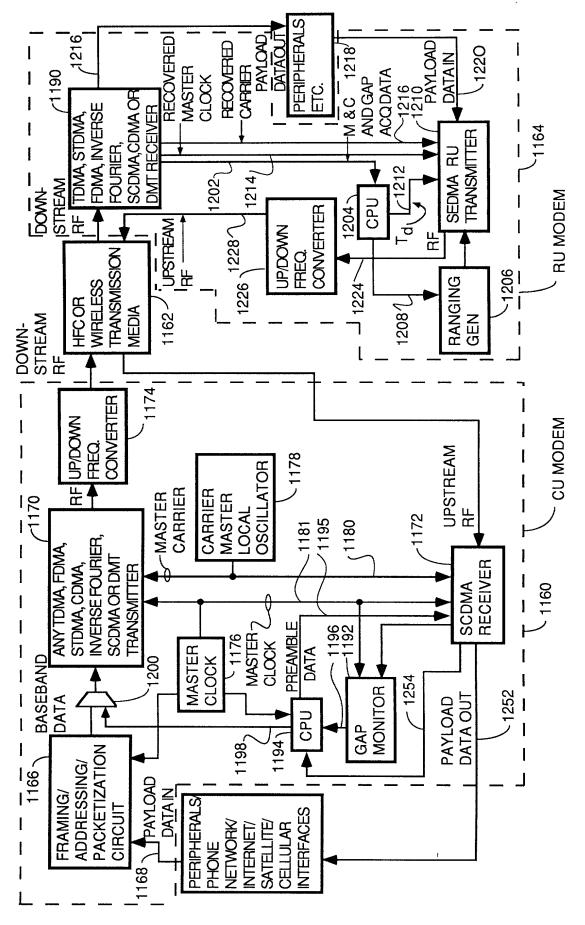
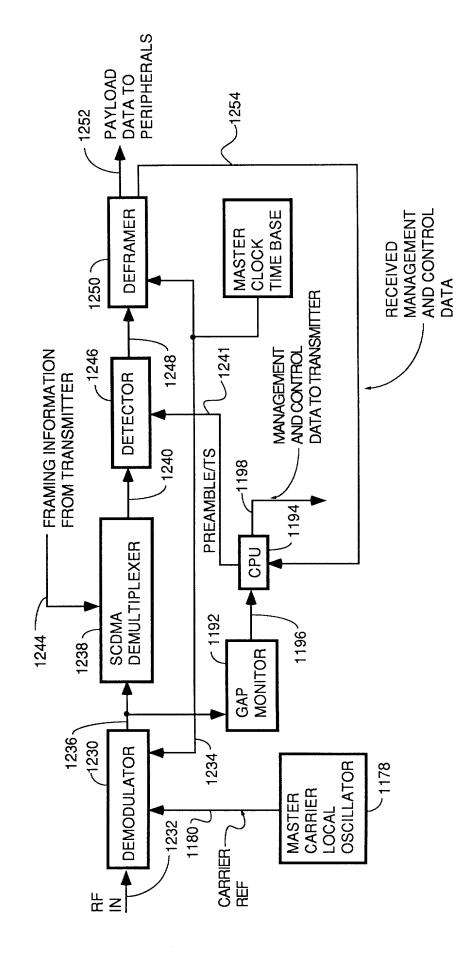


FIG. 54



SIMPLE CU SPREAD SPECTRUM RECEIVER FIG. 55

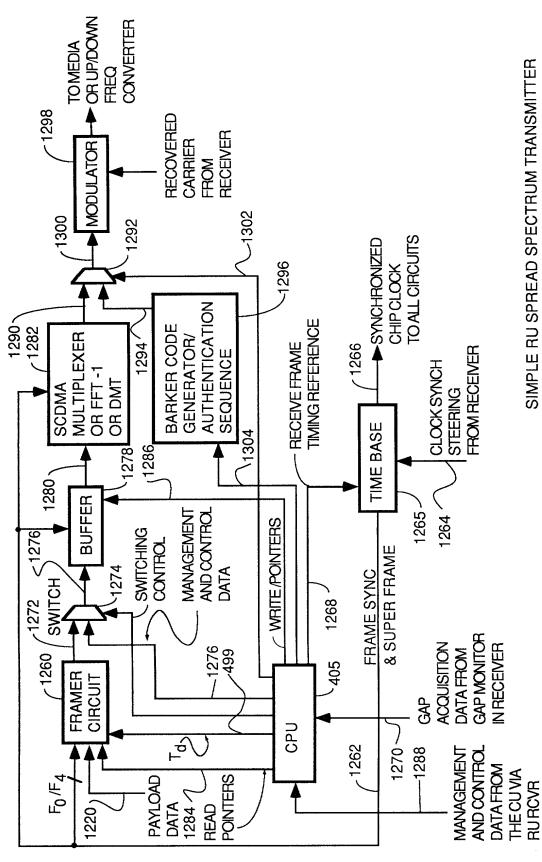
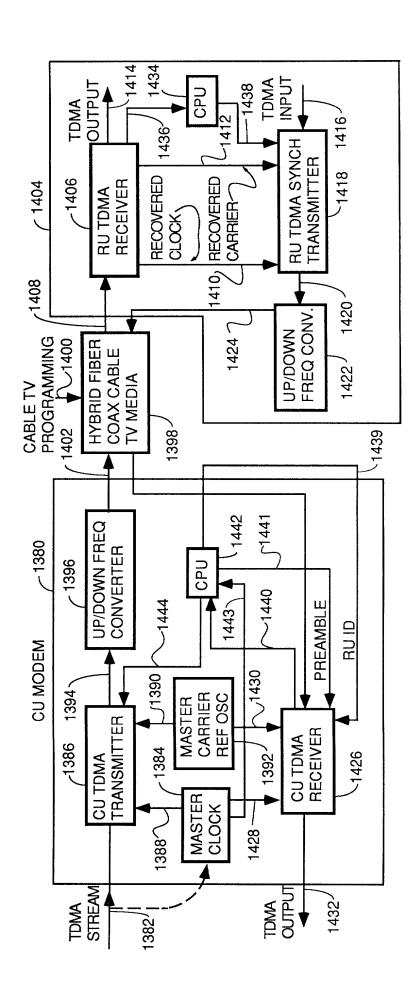


FIG. 56



SYNCHRONOUS TDMA SYSTEM

FIG. 57

OFFSET	1B .	ASIC	2A ASIC			
(CHIPS)	RGSRH	RGSRL	RGSRH	RGSRL		
0	0x0000	0x8000	0x0001	0x0000		
1/2	0x0000	0xC000	0x0001	0x8000		
1	0x0000	0x4000	0x0000	0x8000		
-1	0x0001	0x0000	0x0002	0x0000		

FIG. 58

TRAINING ALGORITHM

SE FUNCTION

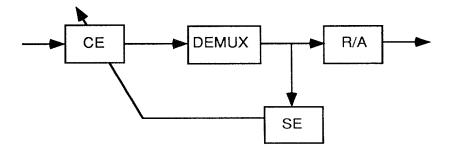
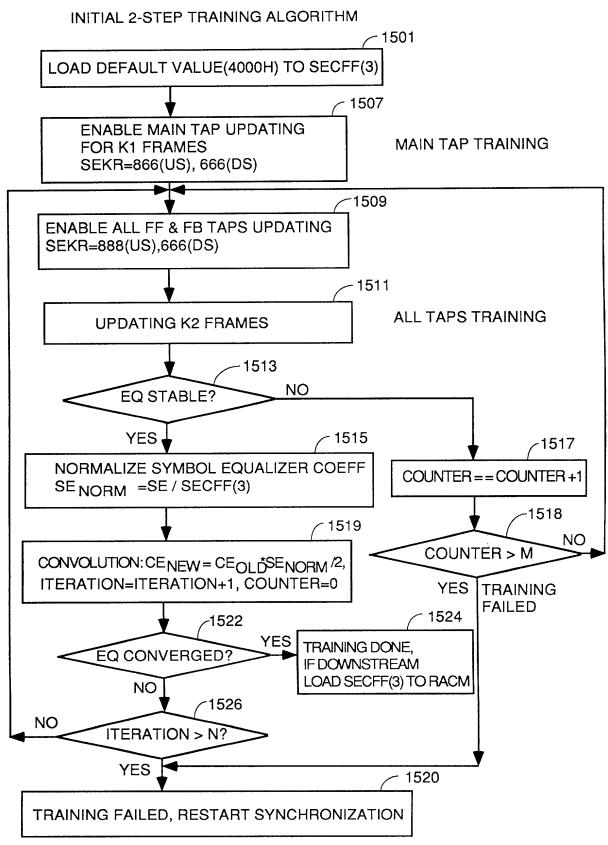
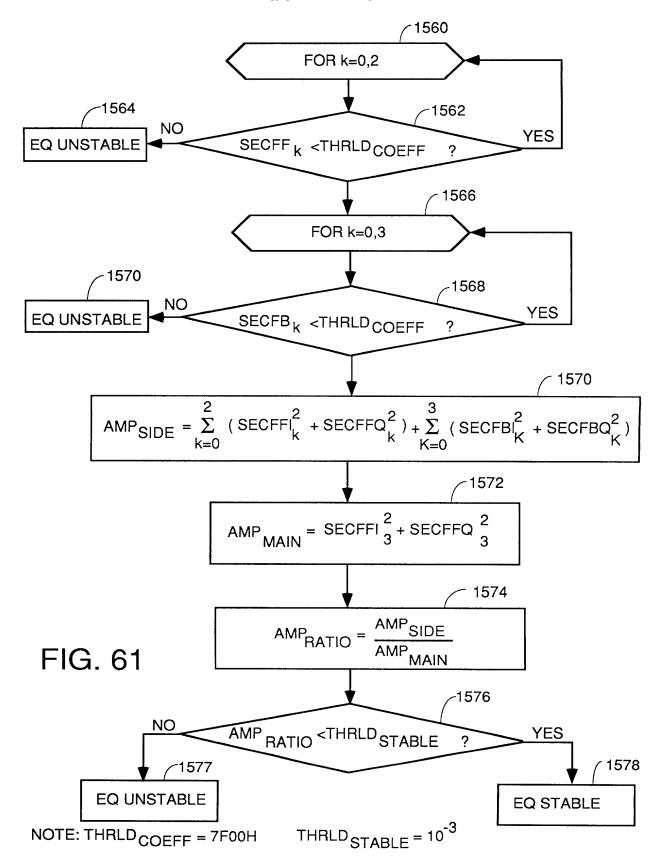


FIG. 59

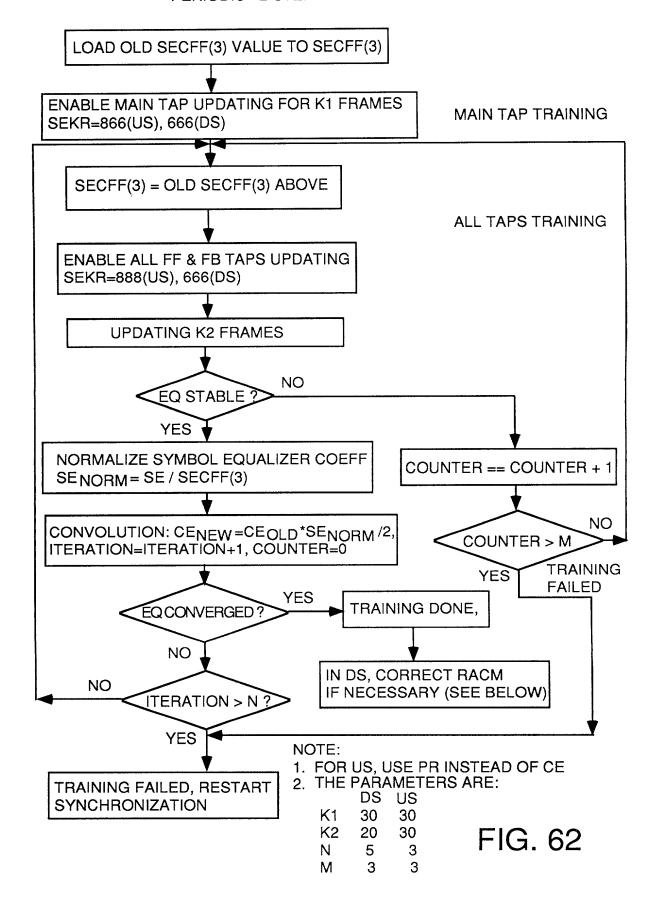


2-STEP INITIAL EQUALIZATION TRAINING FIG. 60

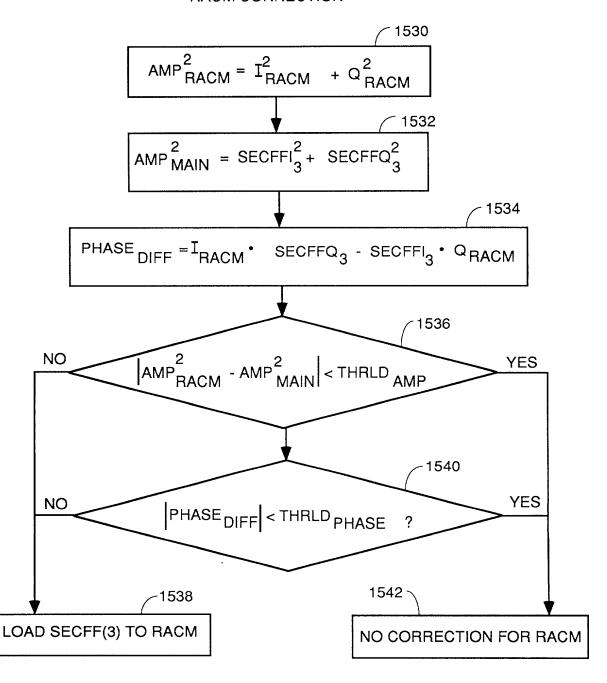
EQ STABILITY CHECK



PERIODIC 2-STEP TRAINING ALGORITHM



RACM CORRECTION



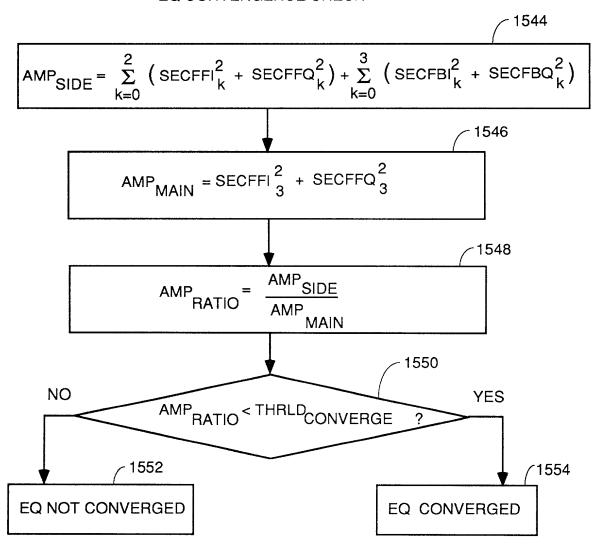
NOTE: THRLD_{AMP} = TBD

THRLD_{PHASE} = TBD

ROTATIONAL AMPLIFIER CORRECTION

FIG. 63

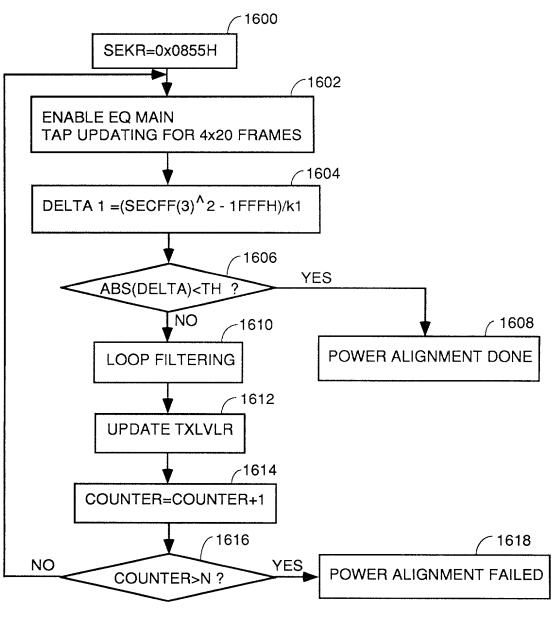
EQ CONVERGENCE CHECK



NOTE: THRLD CONVERGE = 10⁻⁵

FIG. 64

POWER ALIGNMENT FLOW CHART



NOTE: TH = 600HN = 12

FIG. 65

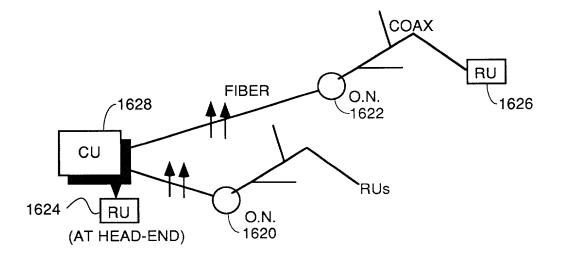
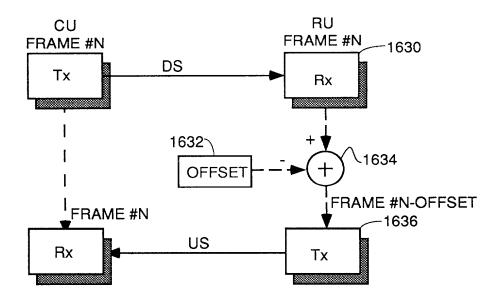


FIG. 66



TOTAL TURN AROUND (TTA) IN FRAMES = OFFSET FIG. 67

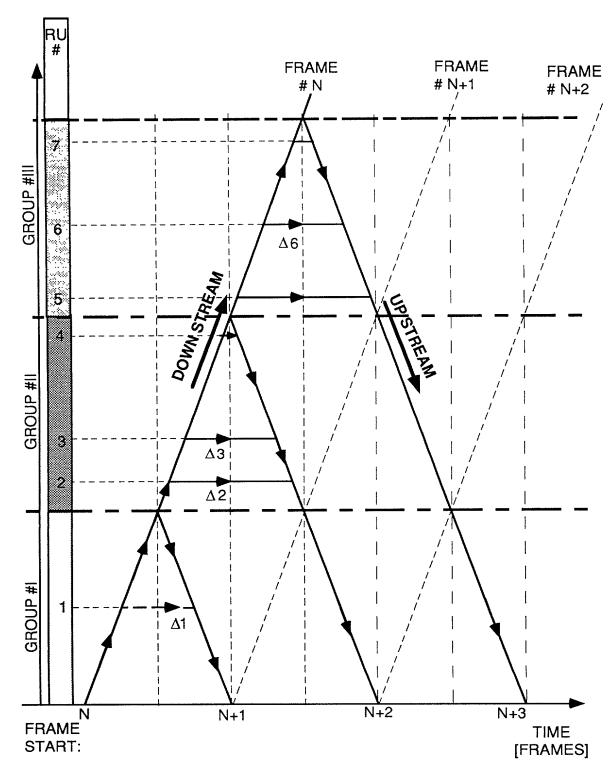
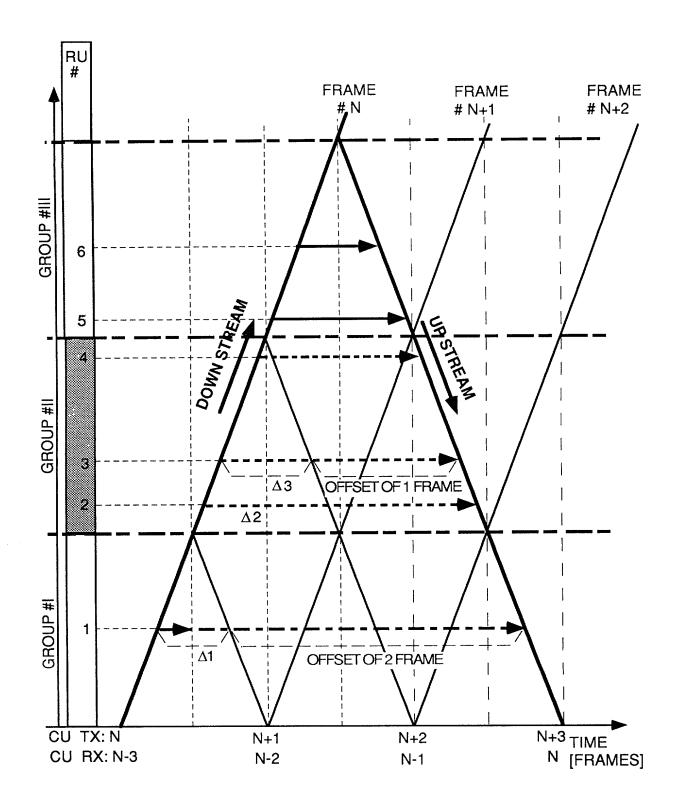


FIG. 68



CONTROL MESSAGE (DOWNSTREAM) AND FUNCTION (UPSTREAM) PROPAGATION IN A 3 FRAMES TTA CHANNEL

FIG. 69

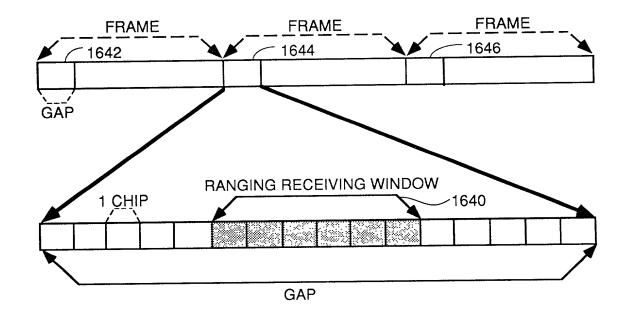
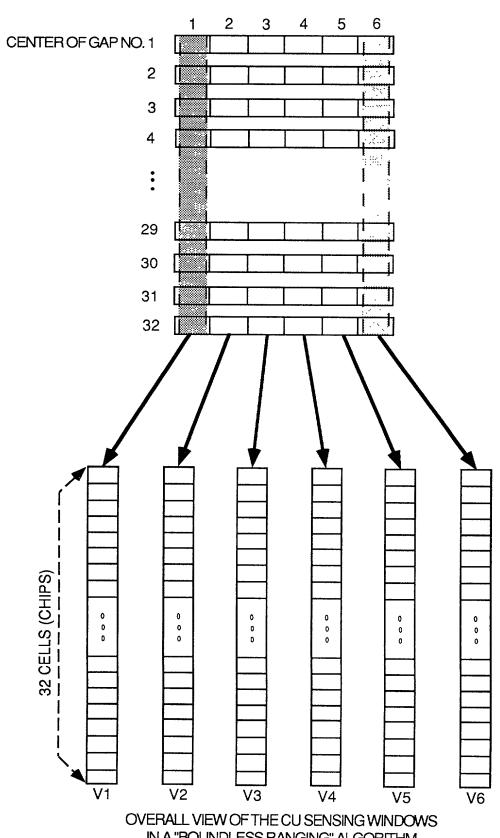


FIG. 70



IN A "BOUNDLESS RANGING" ALGORITHM FIG. 71

CHIP\FR	1	2	3	4	5	6	7		33
1	0	0	1	0	0	1	1	•••	0
2	1	0	0	1	1	1	1	•••	
3	0	0	0		1	1			
4	0	0	0	1	0	0	0	•••	0
5	0	1	0	0	1				
6	0	0	1	1	1				
7	0	0	0		1				
8	0	0	0	0	1	0	0	•••	·

FIG. 72